

H-unitary and Lorentz matrices

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1. Introduction

$M_n = M_n(\mathbb{F})$: $n \times n$ matrices over $\mathbb{F} = \mathbb{C}$ or $\mathbb{F} = \mathbb{R}$.

Let $H^* = H \in M_n$ be invertible.

Define an indefinite inner product on \mathbb{F}^n by

$$[x, y]_H = [x, y] = y^* H x.$$

A matrix $A \in M_n$ is called *H-unitary* if

$$[Ax, Ay] = [x, y] \text{ for all } x, y \in \mathbb{F}^n,$$

equivalently,

$$A^* H A = H.$$

When $H = I$ we get the usual inner product and the unitary matrices.

Proposition If $S \in M_n$ is invertible, then $A \in M_n$ is H -unitary if and only if $S^{-1}AS$ is S^*HS -unitary. Thus, we can often consider the case $H = J = J_{p,q} = I_p \oplus -I_q$.

Notation

$\mathcal{U}(H)$: the group of H -unitary matrices.

$\mathcal{U}_{p,q}$: the group of unitary matrices of the form $U_1 \oplus U_2$ with $U_1 \in M_p$ and $U_2 \in M_q$.

Note that $\mathcal{U}_{p,q}$ is a subgroup of $\mathcal{U}(J_{p,q})$.

Some Motivations

- * Group Theory
- * Physics - Lorentz matrices: $A^t H A = H$ for $H = I_3 \oplus [-1]$
- * Numerical analysis, differential equations, electrical engineering - functions with values in $\mathcal{U}(H)$.

Our goal

- * Give a gentle introduction via the canonical form, and
- * discuss some recent results on linear preservers.

Some related recent work

- * Higham, Horn, Merino, Edward Poon have obtained some interesting results recently.
- * Bebiano, Providencia, Rodman, Tsing, Uhlig, Li, etc. have studied the subject via H -numerical ranges.

2. CS Decomposition

CS (cos – sin) decomposition of unitary matrices

For any unitary matrix A there are matrices $X, Y \in \mathcal{U}_{p,q}$ such that

$$XAY = I_r \oplus \begin{pmatrix} C & S \\ -S^t & C \end{pmatrix} \oplus I_s,$$

where $C, S \in M_{p-r}$ are diagonal matrices with positive diagonal entries satisfying $C^2 + S^2 = I_{p-r}$.

CS (cosh – sinh) decomposition for J -unitary matrices

Theorem 1 A matrix $A \in \mathcal{U}(J_{p,q})$ if and only if there exist $X, Y \in \mathcal{U}_{p,q}$ such that

$$XAY = I_r \oplus \begin{pmatrix} \sqrt{I_{p-r} + D^2} & D \\ D & \sqrt{I_{p-r} + D^2} \end{pmatrix} \oplus I_s,$$

where $D \in M_{p-r}$ is a diagonal matrices with positive diagonal entries d_1, \dots, d_r determined by the singular values of A :

$$\sqrt{1 + d_1^2} \pm d_1, \dots, \sqrt{1 + d_r^2} \pm d_r, \underbrace{1, \dots, 1}_{n-2r}.$$

Proof. Let

$$A = \begin{pmatrix} A_{11} & A_{12} \\ A_{21} & A_{22} \end{pmatrix} \quad \text{with } A_{11} \in M_p.$$

Suppose $U \in M_p$ and $V \in M_q$ are such that A_{12} has singular value decomposition UDV . Let

$$X = U \oplus I_q \quad \text{and} \quad Y = I_p \oplus V.$$

Then with some adjustments of X and Y , XAY has the desired form. ■

Theorem 2 Let $A \in M_n$. Then $A \in \mathcal{U}(J_{p,q})$ if and only if there is $U \in \mathcal{U}_{p,q}$ such that UA has any one of the following forms:

$$(a) \begin{pmatrix} \sqrt{I_p + MM^*} & M \\ M^* & \sqrt{I_q + M^*M} \end{pmatrix} \text{ for a } p \times q \text{ matrix } M,$$

$$(b) \exp \left(\begin{pmatrix} 0_p & L \\ L^* & 0_q \end{pmatrix} \right) \text{ for a } p \times q \text{ matrix } L.$$

$$(c) \begin{pmatrix} I_p & K \\ K^* & I_q \end{pmatrix} \begin{pmatrix} I_p & -K \\ -K^* & I_q \end{pmatrix}^{-1} \text{ for a } p \times q \text{ matrix } K$$

with all singular values less than one.

Proof. By Theorem 1, XAY is a direct sum of 2×2 matrices. So, the problem reduces to 2×2 matrix computations. ■

Remarks

1. One can write analogous conditions AV with $V \in J_{p,q}$. We omit the statements.
2. Notice that the matrices in (a), (b), and (c) are just the positive definite part of the polar decomposition of A . Hence, they are the same as $(A^*A)^{1/2}$.

Applications in Physics

Corollary Suppose $A \in \mathcal{U}(J_{p,q})$ and $U = U_1 \oplus U_2 \in \mathcal{U}_{p,q}$ are such that

$$UA = \begin{pmatrix} I_p & K \\ K^* & I_q \end{pmatrix} \begin{pmatrix} I_p & -K \\ -K^* & I_q \end{pmatrix}^{-1}.$$

as in Theorem 2 (c). Let $(X_0 | Y_0), (X_1 | Y_1) \in M_{r \times p} \times M_{r \times q}$ be *initial vectors* and *final vectors* of A , respectively, i.e.,

$$(X_0 | Y_0)A = (X_1 | Y_1).$$

Then

$$X_0 U_1^* (I_p - K K^*) = X_1 (I_p + K K^*) - 2Y_1 K^*, \text{ and}$$

$$Y_0 U_2^* (I_q - K^* K) = Y_1 (I_q + K^* K) - 2X_1 K.$$

In particular, If $X_0 \in M_p(\mathbb{F})$ is invertible, then

$$X_0^{-1}[X_1(I_p + KK^*) - 2Y_1K^*]$$

is a constant matrix, that is, independent of $(X_0 | Y_0)$ and of $(X_1 | Y_1)$. Similarly, if $Y_0 \in M_q(\mathbb{F})$ is invertible, then

$$Y_0^{-1}[Y_1(I_q + K^*K) - 2X_1K]$$

is a constant matrix.

Suppose $\mathbb{F} = \mathbb{R}$ and $A = \begin{pmatrix} A_{11} & A_{12} \\ A_{21} & A_{22} \end{pmatrix} \in \mathcal{U}(J_{p,q})$. Define

$$\sigma_+(A) = \text{sign}(\det(A_{11})) \text{ and } \sigma_-(A) = \text{sign}(\det(A_{22})).$$

Corollary Suppose $\mathbb{F} = \mathbb{R}$ and $A, B \in \mathcal{U}(J_{p,q})$. Then

$$\sigma_+(A)\sigma_+(B) = \sigma_+(AB) \quad \sigma_-(A)\sigma_-(B) = \sigma_-(AB).$$

Some algebraic and geometric structures

Corollary Suppose H is congruent to $J_{p,q}$. Then $\mathcal{U}(H)$ is homeomorphic to $\mathcal{U}_p \times \mathcal{U}_q \times \mathbb{F}^{pq}$.

If $\mathbb{F} = \mathbb{R}$, $\mathcal{U}(H)$ is a real analytic manifold consisting of four arc-wise connected components, and the identity component is locally isomorphic to

$$\mathbb{R}^{p(p-1)/2} \times \mathbb{R}^{q(q-1)/2} \times \mathbb{R}^{pq}.$$

If $\mathbb{F} = \mathbb{C}$, $\mathcal{U}(H)$ is a real analytic manifold consisting of one arc-wise connected component which is locally isomorphic to

$$\mathbb{R}^{p^2} \times \mathbb{R}^{q^2} \times \mathbb{R}^{2pq}.$$

Corollary $\mathcal{U}_{p,q}$ is a maximal bounded subgroup of $\mathcal{U}(J_{p,q})$.

Theorem 3 Suppose $A = \begin{pmatrix} A_{11} & A_{12} \\ A_{21} & A_{22} \end{pmatrix} \in M_n$ with $A_{11} \in M_p$ and $A_{22} \in M_q$. Then $A \in \mathcal{U}(J_{p,q})$ if and only if

$$X = A_{11}(I_p + A_{21}^* A_{21})^{-1/2} \in \mathcal{U}_p,$$

$$Y = A_{22}(I_q + A_{12}^* A_{12})^{-1/2} \in \mathcal{U}_q,$$

$$\text{and } X^* A_{12} = A_{21}^* Y.$$

3. Some Factorization Results

3.1 Products of positive definite $J_{p,q}$ -unitary matrices

Fact A matrix $A \in M_n(\mathbb{F})$ is a product of two positive definite matrices if and only if A is diagonalizable and has positive eigenvalues.

Proof. If $A = S^{-1}DS$, then $A = S^{-1}(S^{-1})^*S^*DS$. For the converse, if $A = PQ$ for some positive definite matrices P and Q , then A is similar to $Q^{1/2}PQ^{1/2}$

Deeper result Every $A \in M_n$ with positive determinant is a product of no more than five positive definite matrices.

Theorem 4 Let $A \in \mathcal{U}(J_{p,q})$. The following are equivalent.

(a) A is the product of two matrices of the form

$$\begin{pmatrix} \sqrt{I_p + XX^*} & X \\ X^* & \sqrt{I_q + X^*X} \end{pmatrix}, \quad X \in M_{p \times q}(\mathbb{F}).$$

(b) A is $J_{p,q}$ -unitarily similar to a matrix of the form

$$\begin{pmatrix} \sqrt{I_p + XX^*} & X \\ X^* & \sqrt{I_q + X^*X} \end{pmatrix}, \quad X \in M_{p \times q}(\mathbb{F}).$$

(c) A has positive eigenvalues and is diagonalizable.

3.2 Products of reflections / Householder transforms

In $M_n(\mathbb{R})$, a matrix of the form $T_v = I - 2vv^t$ is called a reflection, and $T_v(x) = x - 2(v^t x)v$ is just a reflection of the vector x about the plane v^\perp .

If v is in the linear span of two basic vectors e_i and e_j , then we say that T_v is an *elementary reflection* or *Householder transform*. Thus, an elementary reflection is a direct sum of a two by two matrix and I_{n-2} .

Fact Every orthogonal/unitary matrix is the product of no more than $n(n-1)/2 + 1$ elementary reflections.

For the indefinite inner product $[x, y]_H = y^t H x$, define a *reflection* by $T_v = I - 2vv^t H / (v^t H v)$ for $v \in \mathbb{F}^n$ with $v^t H v \neq 0$. Then T_v is an H -unitary matrix such that

$$T_v(x) = x - 2[x, v]v / [v, v].$$

Similarly, one can define *elementary reflections*.

Theorem 6 A matrix $A \in M_n(\mathbb{R})$ is $J_{p,q}$ -unitary if and only if it is a product of at most

$$f(p, q) = p(p - 1) + q(q - 1) + \min\{p, q\} + 4$$

so many elementary reflections.

Remark Using (general) reflections instead of elementary reflections, one can express a matrix in $\mathcal{U}(p, q)$ as a product of no more than n reflections, a result due to Cartan.

4. Other canonical forms

In connection to stability theory or differential equations, one needs the canonical form in terms of the Jordan forms of A . To get this, we use the idea of linear fractional transforms.

A matrix $K \in M_n$ is called *H-skewadjoint* if

$$[Kx, y] = -[x, Ky] \text{ for every } x, y, \in \mathbb{F}^n,$$

$$\text{i.e., } HKH^{-1} = -K^*.$$

Assume that $H \in M_n$ is an invertible Hermitian (symmetric in the real case) matrix.

Proposition Suppose A is H -unitary, and $\mu, \xi \in \mathbb{F}$ satisfy $|\mu| = 1$ with $\det(A - \mu I) \neq 0$ and $-\bar{\xi} \neq \xi$ if $\mathbb{F} = \mathbb{C}$. Then the operator

$$K = (\xi A + \mu \bar{\xi} I)(A - \mu I)^{-1}$$

is H -skewadjoint such that $\det(K - \xi I) \neq 0$.

Conversely, suppose $K \in M_n$ is H -skewadjoint, and $\mu, \xi \in \mathbb{F}$ satisfy $|\mu| = 1$, $\det(K - \xi I) \neq 0$, and $-\bar{\xi} \neq \xi$ if $\mathbb{F} = \mathbb{C}$. Then

$$A = \mu(K + \bar{\xi} I)(K - \xi I)^{-1}$$

is H -unitary such that $\det(A - \mu I) \neq 0$.

5. Linear preservers

One often considers linear preservers of functions, relations, and subsets.

- * [Frobenius, 1879] A linear operator $\phi : M_n \rightarrow M_n$ satisfies $\det(A) = \det(\phi(A))$ for all $A \in M_n$ if and only if there are $M, N \in M_n$ with $\det(MN) = 1$ such that ϕ has the form

$$A \mapsto MAN \quad \text{or} \quad A \mapsto MA^t N.$$

- * [Hua, 1951] A transformation $\phi : M_n \rightarrow M_n$ satisfies $\text{rank}(\phi(A) - \phi(B)) = 1$ whenever $\text{rank}(A - B) = 1$ if and only if there are $M, N, R \in M_n$ with $\det(MN) \neq 0$ such that ϕ has the form

$$A \mapsto MAN + R \quad \text{or} \quad A \mapsto MA^t N + R.$$

- * [Marcus, 1959] A linear operator $\phi : M_n \rightarrow M_n$ satisfies $\phi(\mathcal{U}(I_n)) \subseteq \mathcal{U}(I_n)$ if and only if there are unitary matrices $U, V \in M_n$ such that ϕ has the form

$$A \mapsto UAV \quad \text{or} \quad A \mapsto UA^tV.$$

- * [Cheung & Li, 2002] There is a linear operator $\phi : M_n \rightarrow M_m$ such that $\phi(\mathcal{U}(I_n)) \subseteq \mathcal{U}(I_m)$ if and only if $m = kn$ and there are unitary matrices U and V such that

$$A \mapsto U[(I_{k_1} \otimes A) \oplus (I_{k_2} \otimes A^t)]V.$$

Theorem 7 Let $H_1 \in M_n$ and $H_2 \in M_m$ be invertible Hermitian matrices. There is a linear transformation $\phi : M_n \rightarrow M_m$ such that $\phi(\mathcal{U}(H_1)) \subseteq \mathcal{U}(H_2)$ if and only if m is a multiple of n , and there exist invertible matrices $S \in M_m$, $U, V \in \mathcal{U}(H_2)$ such that

$$S^* H_2 S = [(I_a \oplus -I_b) \otimes H_1] \oplus [(I_c \oplus -I_d) \otimes (H_1^{-1})^t],$$

and ϕ has the form

$$A \mapsto US[(I_{a+b} \otimes A) \oplus (I_{c+d} \otimes A^t)]S^{-1}V,$$

where $a, b, c, d \in \mathbb{N}$ satisfy $(a + b + c + d)n = m$.

Theorem 8 Let $H_1 \in M_n$ and $H_2 \in M_m$ be invertible Hermitian matrices such that H_1 has inertia (p, q) and H_2 has inertia (r, s) . The following conditions are equivalent.

- (a) There exists a linear transformation $\phi : M_n \rightarrow M_m$ such that $\phi(\mathcal{U}(H_1)) \subseteq \mathcal{U}(H_2)$.
- (b) There exists an invertible matrix $S \in M_m$ satisfying

$$S^* H_2 S = [(I_a \oplus -I_b) \otimes H_1] \oplus [(I_c \oplus -I_d) \otimes (H_1^{-1})^t].$$

- (c) There are nonnegative integers u and v such that $(r, s) = u(p, q) + v(q, p)$.
- (d) Either (i) $p - q = r - s = 0$ and $(u + v)p = r$, or (ii) $p \neq q$ and $(u, v) = (pr - qs, ps - qr)/(p^2 - q^2)$ is a pair of nonnegative integers.

Proof.

1. Reduction to the case when $(H_1, H_2) = (J_{p,q}, J_{r,s})$.
2. Replacing ϕ by $A \mapsto \phi(I_n)^{-1}\phi(A)$ so that $\phi(I_n) = I_m$.
3. For diagonal matrices D , we have $\phi(D) = U^*(I_t \otimes D)U$ for some unitary $U \in M_m$.
4. Show that for symmetric $A \in M_n$,

$$\phi(A) = U^*[(I_p \otimes A) \oplus (I_q \otimes A^t)]U$$

for some unitary $U \in M_m$.

5. Fix up the skew-symmetric matrices.
6. Deduce the relation between H_1 and H_2 . ■

Further research

- * Study applications of the results, or develop results needed in applications.
- * Extend the techniques to study other types of matrices.
- * Find shorter conceptual proof of the preserver result.
- * Consider the real case.

[Wei, 1972] Except for $n = 2, 4, 8$, a linear operator $\phi : M_n(\mathbb{R}) \rightarrow M_n(\mathbb{R})$ satisfies $\phi(\mathcal{U}(I_n)) \subseteq \mathcal{U}(I_n)$ if and only if there are unitary matrices $U, V \in M_n$ such that ϕ has the form

$$A \mapsto UAV \quad \text{or} \quad A \mapsto UA^tV.$$

Thank you for your attention!